

CRAWLER MOUNTED BOOM PLATFORM - ALL IN ONE

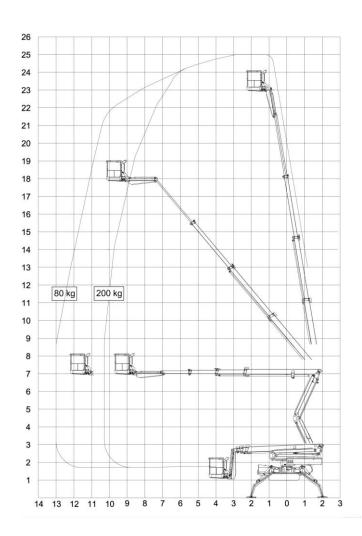
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2500 RXJ Crawler Mounted





Technical data:	2500 RXBJ	2500 RXBDJ
Max. working height	25.0 m	
Max. outreach	13.0 m	
Max. basket load	200 kg	
Fly jib (jib and basket)	2.70 m	
Basket size	1.25x0.8x1.1m	
Rotation	± 355°	
Power sources: Diesel engine		14 kW/18.8 hp
Generator		24 V/22 A
Battery	24V/400Ah/5h	24V/200Ah/5h
Charger	24 V/30 A	
Travelling length	6.00/6.60 m	
Travelling height	2.07 m	
Travelling width	1.10 m	
Operational width	4.60 / 3.75 m	
Total weight approx.	3975 kg	
Gradeability: Across slope up to	30% (16.7°)	
Up and down slope up to	35% (19.3°)	
Stabilization up to	40% (21.8°)	
Proportional controls	+	
230 V outlet in basket	+	
Wireless remote control (drive only)	0	
White non-marking tracks	0	
Automatic set-up and take-down	0	

+ Standard O Optional

HIGH SPECIFICATION – HUGE OUTREACH









- The 2500 RXBDJ has a maximum working height of 25 m, an outreach of up to 13 m and actually provides over 10 m side reach with a full 200 kg basket load. A zero tail swing articulating riser gives 7 m up-and-over free clearance at full stretch. The long movable jib makes final adjustment. The transit length is only 6.60 m but can be further reduced to 6.00 m without the easy removable basket. Standard width is down to 1.10 m.
- The lift is powered by a Kubota diesel engine for outdoor use but a 200 Ah battery pack makes the lift equally efficient in indoor environments. No hazardous extension cords linked to mains are needed when travelling down the atrium lanes. Additionally battery power supplies minimum noise and no exhaust green operation everywhere.
- The stabilizers allow the machine to be used on uneven levels up to 40%. Gradeability is also 35%, equivalent to 19.3° and combined with the non-skid crawler belts the platform can be used on most terrains. These features enable the machine to negotiate park and woodland areas and town centres where kerbs or other obstacles must be overcome.
- The crawler chassis is designed to be both strong and to disperse the machine's weight widely. This is important when
 operating on more sensitive surfaces such as tiles, marble, flagged foot paths, wooden floorings, or in applications
 where the platform is craned into storey buildings where high reach is required but low weight necessary.